WHEN TRUST MATTERS

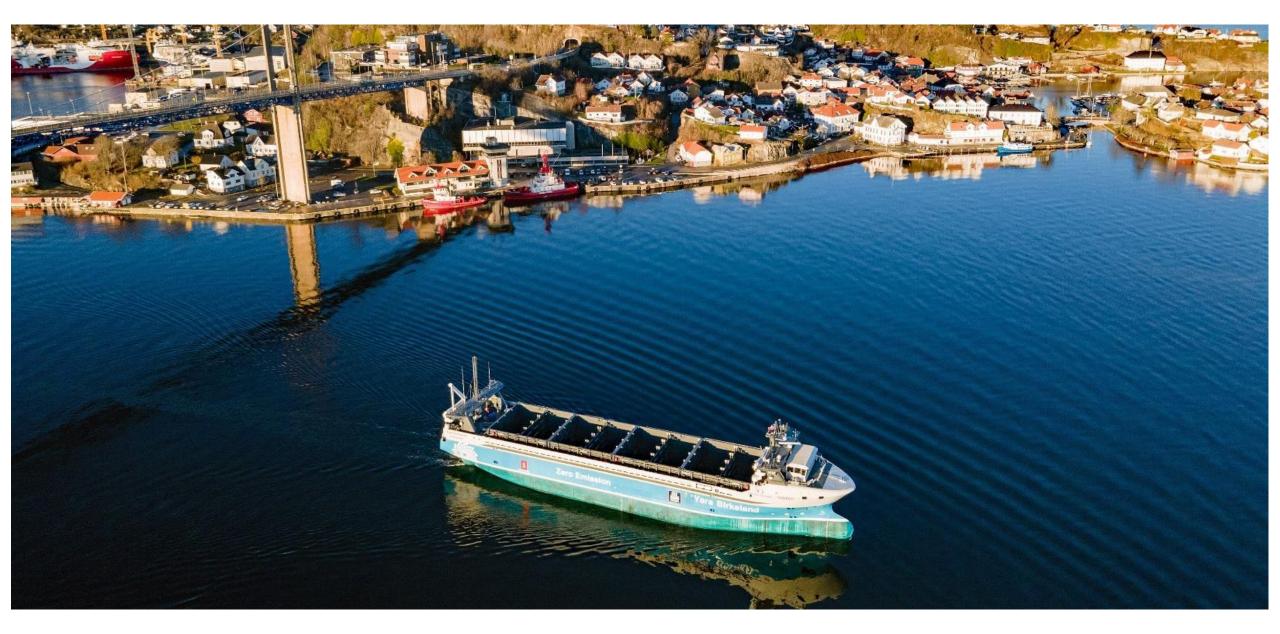


Agent transparency and human performance in the context of autonomous collision avoidance

ICMASS - 2024

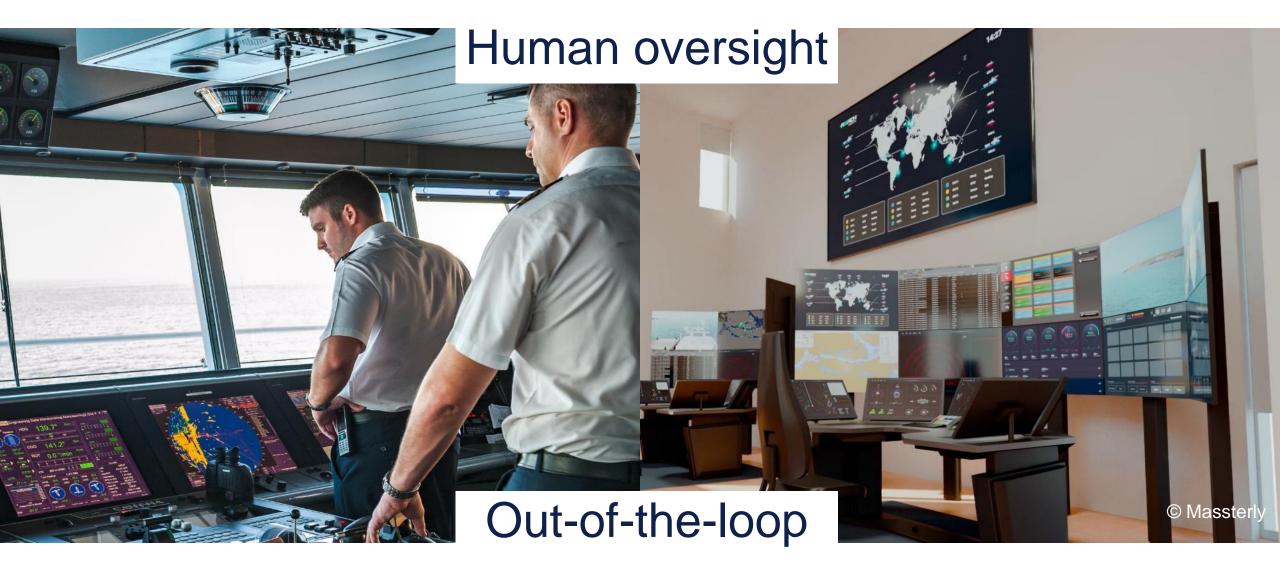
Koen van de Merwe, koen.van.de.merwe@dnv.com 30 October 2024





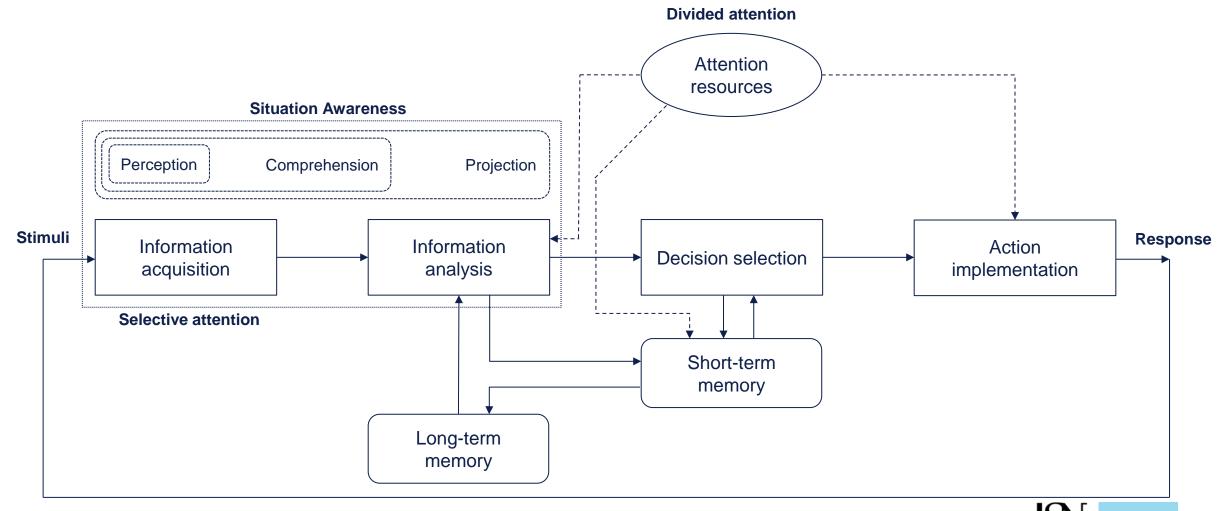


Decision support "Fully" autonomous









Feedback

"Restoring the information loop"

• Transparency is about making the system understandable and predictable to its users Endsley, Bolte, and Jones (2003)

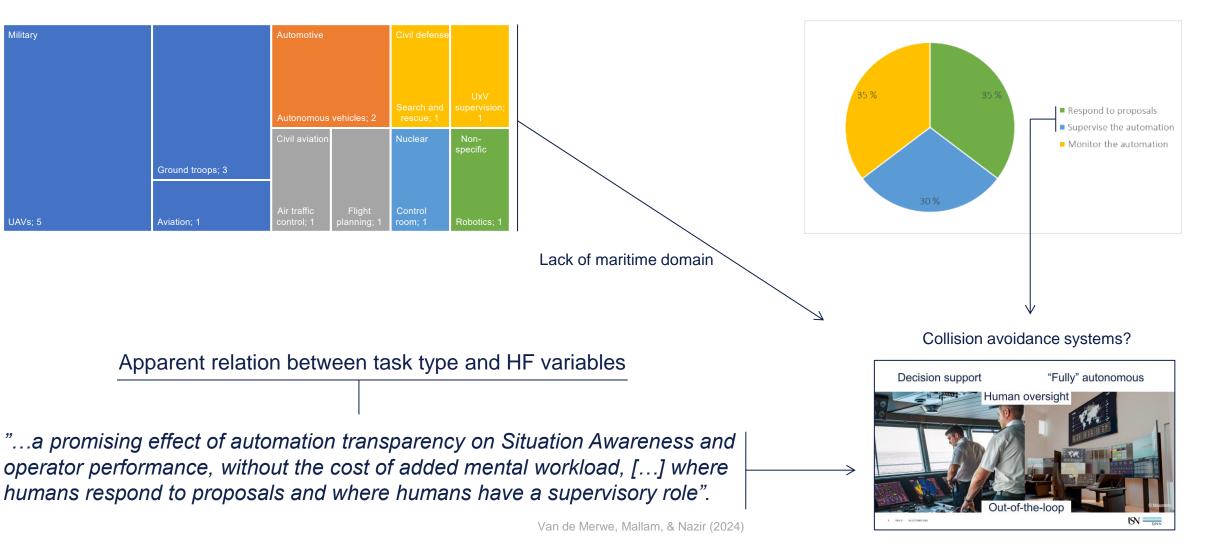
 Its goal is to enable operators to maintain proper <u>Situation</u> <u>Awareness of the system</u> in its environment without becoming overloaded

Mercado et al. (2016)

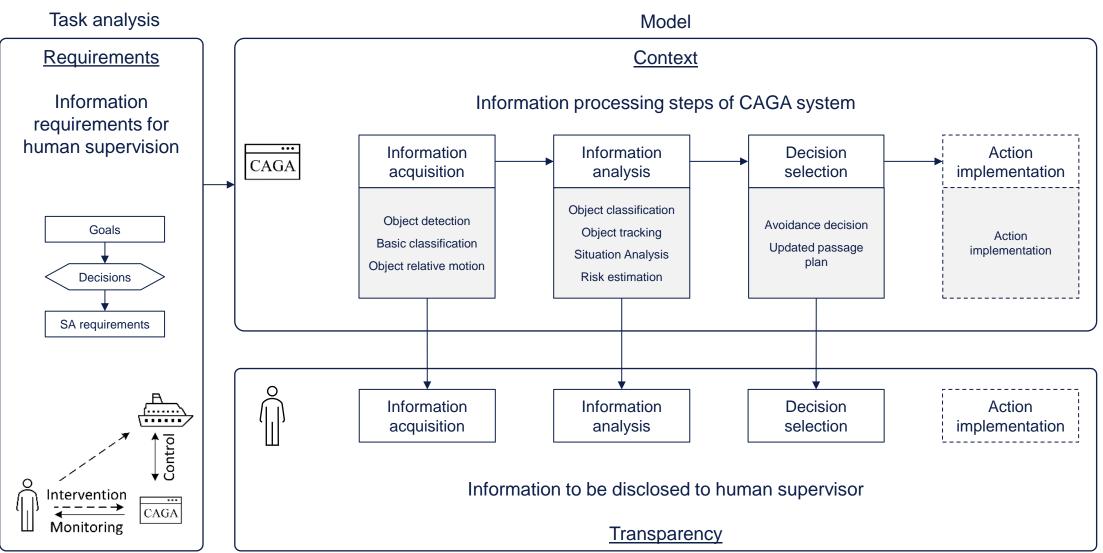
How does agent transparency support human performance in supervisory control?



Exploring transparency in the literature



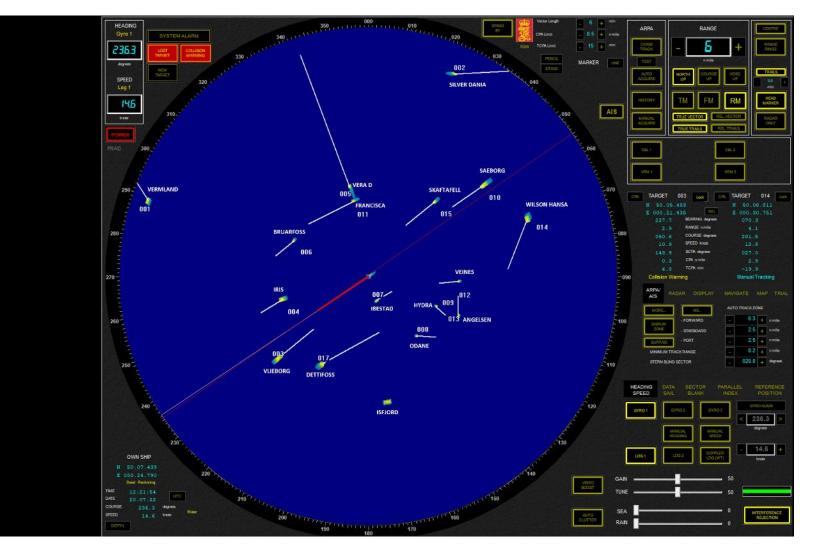
From information requirements to transparency





Transparency level: None



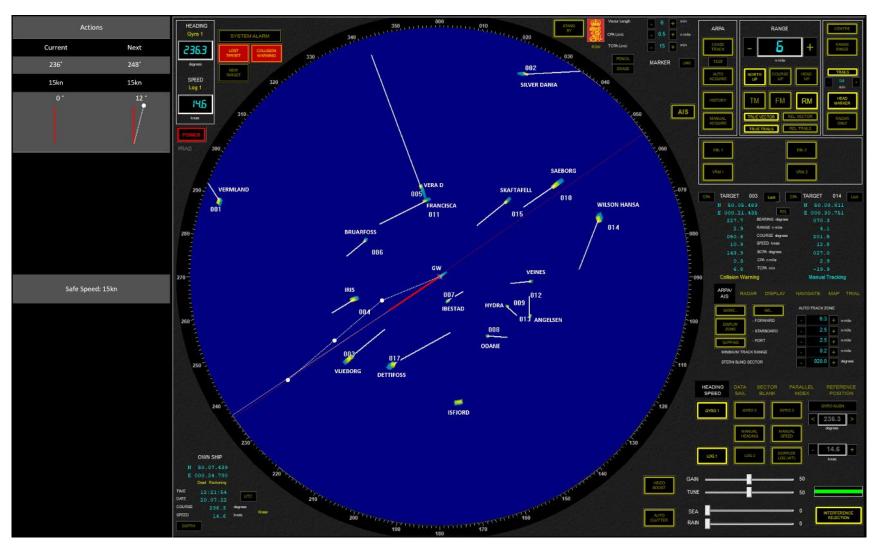


	Information processing steps		
Level of	Information	Information	Decision
transparency Low	acquisition	analysis	selection
Medium (A)		Х	Х
Medium (B)	Х		Х
High	Х	Х	Х



Transparency level: Low



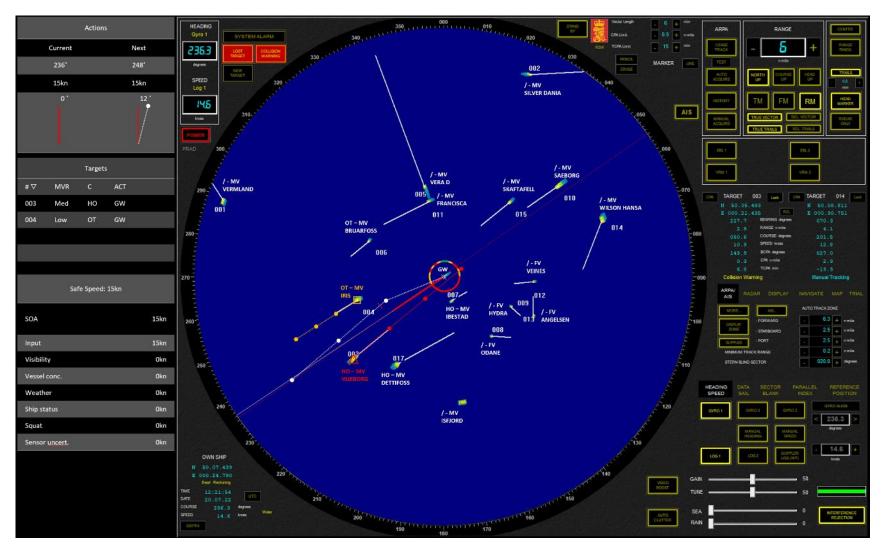


	Information processing steps			
Level of transparency	Information acquisition	Information analysis	Decision selection	
Low			Х	
Medium (A)		Х	Х	
Medium (B)	Х		Х	
High	Х	Х	Х	



Transparency level: Medium (A)



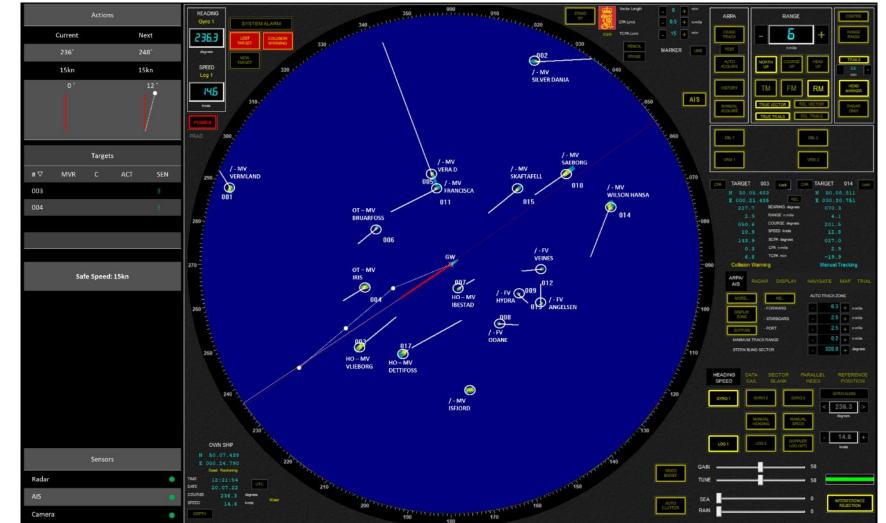


	Information processing steps			
Level of transparency	Information Information acquisition analysis		Decision selection	
Low			Х	
Medium (A)		Х	Х	
Medium (B)	Х		Х	
High	Х	Х	Х	



Transparency level: Medium (B)





Information processing stepsLevel of
transparencyInformation
acquisitionDecision
selectionLow
Medium (A)XXMedium (B)XX

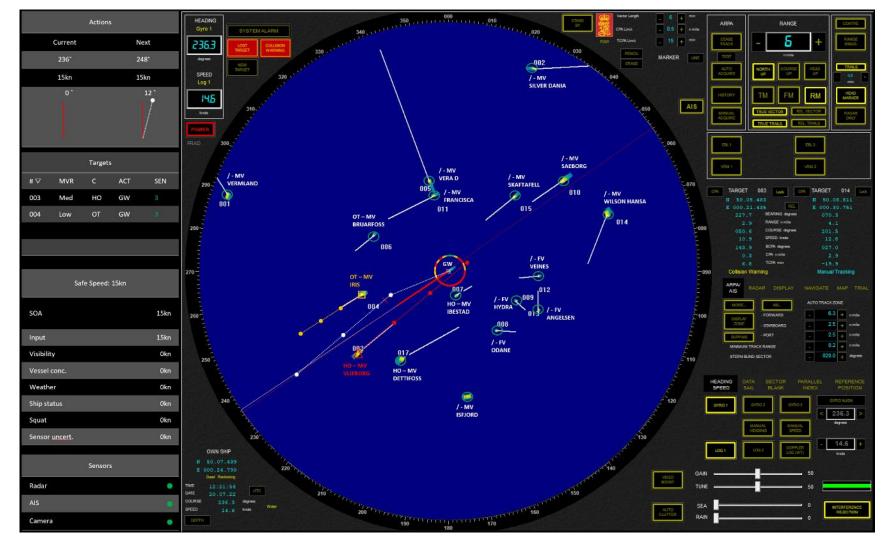
V

V



Transparency level: High





	Information processing steps		
Level of transparency	Information acquisition	Information analysis	Decision selection
Low			Х
Medium (A)		Х	Х
Medium (B)	Х		Х
High	Х	Х	Х



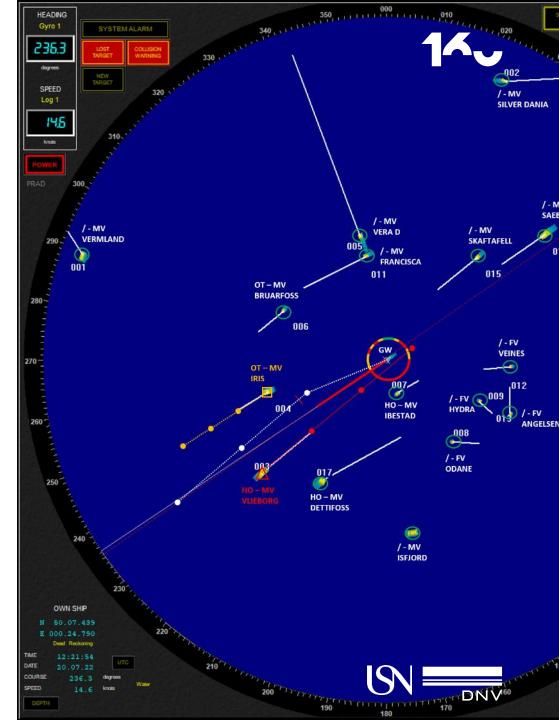
Controlled experiment

- 34 (licensed) navigators
- Dependent variables
 - Transparency (4)
 - Complexity (2)
 - Within-subjects design
 - Randomised stimuli
- Dependent variables
 - Situation Awareness (SAGAT)
 - Task performance (Time)
 - Mental workload (NASA-TLX)
 - Preference
- (Ranking)
- Post-experiment interviews



Experimental results

- Improved Situation Awareness with increased transparency
- <u>Additional time</u> needed to perceive and comprehend the traffic situations
- No effect on mental workload observed
- Participants clearly preferred the medium (A) and high transparency HMIs*, i.e. those that present the system's risk analysis
 Van de Merwe et al (2024b)
- Thematic analysis on interview data showed:
 - Insight into the CAGA system's real-time understanding of the situation
 - Insight into how the CAGA system understands the risk picture



Experimental results

- Mixed methods approach illustrates the role of transparency to address out-of-the-loop performance problem:
 - Experimental results showed which LoT had effect
 - Medium (A) and High
 - Interview results showed <u>why</u>
 - Understand the ship's understanding of the situation
- Transparency and safety critical tasks
 - Ensuring safety is main responsibility of navigator
 - System's analysis = most critical information



Further work

- What are the limits of transparency?
 - Time-limited operations
 - Dynamic transparency
 - Integration of transparency information vs noise
 - Inclusion of grounding avoidance information
 - How to represent uncertainty?
- What is the role of transparency in human-AI teaming?
 - Improved task engagement with transparency?



Designing for Human-Autonomy systems



Automate only if necessary	Use automation for routine tasks, not high-level cognitive functions	Provide support for Situation Awareness, not decisions	Keep operator in control and in the loop	Avoid too many automation modes
Make modes and system states salient	Enforce automation consistency	Avoid advanced queuing of tasks	Avoid use of information cuing	Use methods of decision support to create symbiosis
Provide automation transparency	Ensure logical consistency across features and modes	Minimize logic branches	Map system functions to the user's goals and mental models	Minimize task complexity
Support comprehension of information (L2 SA)	Provide assistance for projections (L3 SA)	Use information filtering carefully	Support assessment of system confidence level	Support assessment of system reliability

Endsley, 2017

Endsley, Bolte, and Jones, 2003



Wrapping up



"This dissertation advocates the relevance of affording human operators with insight into the reasoning of autonomous systems and established transparency as an important prerequisite on the path towards safe and effective human-supervisory control" Van de Merwe (2024)





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Thank you!

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